

Simulink® Real-Time™

R2020b & Later Upgrade User's Guide



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R2022a



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Simulink® Real-Time™ R2020b & Later Upgrade User's Guide

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Upgrade Systems and Models for Release R2020b

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Check model for upgradable Simulink Real-Time features

Check ID: `mathworks.design.slrealtimeUpgrades`

Check the model for Simulink Real-Time features from a previous release that require an upgrade for compatibility with the current release.

Description

This check identifies upgradable Simulink Real-Time features and upgrades the features where possible and recommends manual upgrades when needed. Block forwarding in the `slrealtime` library and the Speedgoat I/O Blockset eases the upgrade process.

Results and Recommended Actions

Condition	Recommended Action
System Target File upgrade	Change the System Target File to <code>slrealtime.tlc</code> .
Simulink Real-Time block upgrades	Upgrades blocks when possible. Identifies blocks for manual upgrade when needed.
Signal Upgrades	Upgrades signals for Instrument object compatibility.
Simulink Real-Time configuration parameter upgrades	Upgrades configuration parameters for toolchain build and real-time application options.

Capabilities and Limitations

You can:

- Run this check on your Simulink Real-Time models from release R2020a and previous releases.

See Also

- “Troubleshoot Model Upgrade for R2020b” on page 1-3
- “Troubleshoot System Upgrade for R2020b” on page 1-5

Troubleshoot Model Upgrade for R2020b

When I build my pre-R2020b Simulink Real-Time models in R2020b, I get build errors. Some of the blocks in my model have the label **Obsolete Simulink Real-Time Block**.

What This Issue Means

For R2020b, you must upgrade the Simulink Real-Time model. A model Upgrade Advisor check is available to support this upgrade.

Try This Workaround

To upgrade your model for Simulink Real-Time R2020b features, use this software upgrade process:

- 1 Install Simulink Real-Time and other required products.
- 2 Install the Simulink Real-Time Target Support Package by using the MATLAB **Add-Ons** menu.
- 3 Install the Speedgoat I/O Blockset. Go to the Speedgoat website.
- 4 Upgrade the target machine software. See “Troubleshoot System Upgrade for R2020b” on page 1-5.
- 5 Open a R2020b or earlier Simulink Real-Time model.
- 6 Run the **Upgrade Advisor**. On the **Modeling** tab, select **Model Advisor > Upgrade Advisor**.
- 7 In the Upgrade Advisor dialog box, select **Check model for upgradable Simulink Real-Time features**. Click the **Run This Check** button. The advisor lists the upgrades that it can apply and the upgrades that require manual changes.
- 8 After the check, click the **Upgrade** button. The advisor upgrades the model by applying all nonmanual changes.

Apply Manual Changes

When the Upgrade Advisor encounters model issues that it cannot resolve by using automated changes, the Upgrade Advisor reports these as **Warning: Some of the features require manual changes**. It is a good practice to copy the text of these warnings and save it for reference as you apply changes to your model.

Apply Speedgoat Utilities

In R2020b, Speedgoat software provides support for configuring interrupts and Ethernet communications.

To configure model interrupts, use a single block from the Speedgoat I/O Blockset. You can use this block for asynchronous subsystems or for triggering the base rate of the model. The list of available interrupt sources reflects the Speedgoat I/O Blockset blocks configured in the model. For more information see the block documentation in `speedgoatlib_utilities`.

To configure additional Ethernet ports on the target machine, the Speedgoat I/O Blockset provides a tool to configure these Ethernet ports. The configuration is specific to the target machine and reflects the labeling on the front plates of the target machine. For more information, in the MATLAB Command Window, type:

```
speedgoat.configureEthernet
```

See Also

“Troubleshoot System Upgrade for R2020b” on page 1-5

Troubleshoot System Upgrade for R2020b

I have upgraded my Simulink Real-Time software for R2020b and have installed the Simulink Real-Time Target Support Package. Now, I cannot download real-time applications to my target computer.

What This Issue Means

The upgrade for release R2020b requires software upgrades to the Simulink Real-Time software and the Speedgoat Target Machine software.

Try This Workaround

In R2020b, the change to a 64-bit POSIX compliant real-time operating system on the target computer requires a software upgrade for your Speedgoat real-time target machine. For this upgrade, the Speedgoat I/O Blockset provides an interactive tool. To retain compatibility with previous versions of MATLAB, you can choose to upgrade the target machine to a dual-boot system where you can select the operating system at startup. Or, you can upgrade the target machine to use only the new operating system. For the upgrade, you need a USB drive and the target machine needs a keyboard and a monitor.

To upgrade your software:

- 1 Install Simulink Real-Time and other required products.
- 2 Install the Simulink Real-Time Target Support Package by using the MATLAB **Add-Ons** menu.
- 3 Install the Speedgoat I/O Blockset. Go to the Speedgoat customer portal.
- 4 To start the target machine upgrade, in the MATLAB Command Window, type:

```
speedgoat.migrateTarget
```

For more information, go to the Speedgoat website.

See Also

More About

- “Troubleshoot Model Upgrade for R2020b” on page 1-3

Troubleshoot MATLAB API Call Upgrade for R2020b

In R2020b, many objects and functions in the Simulink Real-Time API changed.

What This Issue Means

MATLAB® m-scripts written by using the Simulink Real-Time API require updates to run in R2020b and later releases.

Try This Workaround

These tables identify Simulink Real-Time API changes in R2020 and identify new workflows. Use these tables to guide your updates to pre-R2020b m-scripts. For information about Simulink Real-Time in previous releases, see:

<https://www.mathworks.com/help/doc-archives.html>

Target Computer Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
SimulinkRealTime.Application object, ApplicationName property SimulinkRealTime.target object, Application property	Get name of real-time application.	Changed name	Use Target object, Application property.
SimulinkRealTime.target object, Connected property value is 'Yes'.	Get communication status between development and target computers.	Changed name	Use Target object, Connected event. Use connect function to make connection.
close function	Close connection between development and target computers.	Changed name	Use disconnect function to close connection.
getDiskSpace function	Get free space and total space on the drive, in bytes.	Moved to Speedgoat API	Use speedgoat.getDiskSpace function.
load function	Download real-time application to target computer.	Unchanged	Use load function after creating Target object. The real-time application is not automatically loaded as part of the build process.

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
reboot function	Restart target computer.	Unchanged	Use <code>reboot</code> function to restart target computer in standalone mode. Other, previously supported boot modes are not available.
saveparamset	Save a set of parameters to a real-time application	Changed name. Changed workflow.	Use <code>saveParamSet</code> to save the parameter set to a file.
loadparamset	Load a set of saved parameters to a real-time application	Changed name. Changed workflow.	Use <code>importParamSet</code> to Import the parameter set into a <code>ParameterSet</code> object on the development computer.

Real-Time Execution Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
<code>SimulinkRealTime.target</code> object, <code>CPUOverload</code> property	Get CPU overload status.	Changed name	Use <code>Target</code> object, <code>TargetStatus</code> property or <code>ModelStatus</code> property.
<code>SimulinkRealTime.target</code> object, <code>AvgTET</code> property	Get average task execution time.	Changed name	Use <code>Target</code> object, <code>ModelStatus.TETInfo</code> property.
<code>SimulinkRealTime.target</code> object, <code>ExecTime</code> property	Get real-time application execution time.	Changed name	Use <code>Target</code> object, <code>ModelStatus.TETInfo</code> property.
<code>SimulinkRealTime.target</code> object, <code>MaxTET</code> property	Get maximum task execution time.	Changed name	Use <code>Target</code> object, <code>ModelStatus.TETInfo</code> property.
<code>SimulinkRealTime.target</code> object, <code>MinTET</code> property	Get minimum task execution time.	Changed name	Use <code>Target</code> object, <code>ModelStatus.TETInfo</code> property.
<code>SimulinkRealTime.target</code> object, <code>SampleTime</code> property	Get time between samples (step size).	Changed name	Use <code>Target</code> object, <code>ModelStatus.TETInfo.Rate</code> property.
start function	Start execution of real-time application on target computer.	Changed workflow	Use <code>start</code> function to start real-time application and set real-time application options.

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
SimulinkRealTime.target object, Status property	Get execution status of real-time application.	Changed workflow	Use Target object, ModelStatus property or status function.
stop function	Stop execution of real-time application on target computer.	Unchanged	Use stop function.
SimulinkRealTime.target object, StopTime property	Get or set time when real-time application stops running.	Changed workflow	Get by using Target object, ModelStatus.StopTime property and set by using setStopTime function.
SimulinkRealTime.target object, TETLog property	Access storage in the MATLAB workspace for task execution time.	Changed workflow	Use slrtTETMonitor function.

Execution Profiler Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
getProfilerData function	Retrieve profile data object.	Unchanged	Use getProfilerData function. Start the execution profiler before you start the real-time application.
SimulinkRealTime.target object, ProfilerStatus property	Get state of profiler.	Changed workflow	Use Target object, Application property. There are added property values.
resetProfiler function	Reset profiling service state to Ready.	Unchanged	Use resetProfiler function. The profiler resets itself when you start the real-time application.
startProfiler function	Start profiling service on target computer.	Unchanged	Use startProfiler function. Start the execution profiler before you start the real-time application.
stopProfiler function	Stop profiling service on target computer.	Changed limitation	Use stopProfiler function. The profiler auto stop at 1GB is eliminated.

Parameter Tuning Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
setparam function	Change value of tunable parameter in real-time application.	Changed syntax	Use setparam function.
getparam function	Read value of observable parameter in real-time application.	Changed syntax	Use getparam function.
SimulinkRealTime.target object, NumParameters property	Get number of tunable parameters.	Changed workflow	Use Application object and getParameters function.
SimulinkRealTime.target object, Parameters property	Get list of tunable parameters.	Changed workflow	Use Application object and getParameters function.
SimulinkRealTime.target object, ShowParameters property	Set flag to display the list of parameters.	Changed workflow	Use Application object and getParameters function.

Signal Tracing Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
getsignal function	Get single numerical value of a signal.	Changed workflow	Use Instrument object and connectScalar function.
SimulinkRealTime.target object, NumSignals property	Get number of observable signals.	Changed workflow	Use Application object and getSignals function.
SimulinkRealTime.target object, OutputLog property	Access storage in MATLAB workspace for output or Y-vector.	Changed workflow	Use Simulink model "Signal logging" parameter: set_param(bdroot,... 'SignalLogging','on')
SimulinkRealTime.target object, ShowSignals property	Set flag to display the list of signals.	Changed workflow	Use Application object and getSignals function.

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
SimulinkRealTime.target object, Signals property	Get list of observable signals.	Changed workflow	Use Application object and getSignals function.

Signal Logging Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
importLogData function	Import buffered logging data to the active session of the Simulation Data Inspector.	Replaced	Use list function and import function. For more information, see the Target.FileLog object.

Instrumentation Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
addscope function	Create a scope of specified type.	Replaced	Use the Simulation Data Inspector. Use File Log blocks instead File Scope blocks. Use Instrumentobjects instead of Host Scope blocks.
getscope function	Return scope identified by scope number.	Replaced	Use the Simulation Data Inspector. Use File Log blocks instead File Scope blocks. Use Instrumentobjects instead of Host Scope blocks.

Ethernet and EtherCAT Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
Target Computer Settings provided information about Ethernet setup on target computer.	Configure Ethernet ports on target computer	Moved to Speedgoat API	Use <code>speedgoat.configureEthernet</code> function
<code>SimulinkRealTime.etherCAT.filterNotifications</code> function	Display EtherCAT notifications in human-readable format	Changed name	Use <code>slrealtime.EtherCAT.filterNotifications</code> function

Target Computer Settings Operations

R2020a and Previous Command	Command Description	R2020b and Later Command Status	New Workflow
<code>SimulinkRealTime.getTargetSettings</code> function	Get target computer settings.	Changed name	Use <code>getTargetSettings</code> function.

See Also

“Check model for upgradable Simulink Real-Time features” on page 1-2

More About

- “Troubleshoot Model Upgrade for R2020b” on page 1-3
- “Troubleshoot System Upgrade for R2020b” on page 1-5

Troubleshoot S-Function Build Upgrade for R2020b

My pre-R2020b model uses S-Functions. When I migrated my model to the current release, I see this S-Function related message in the build log:

```
undefined reference to 'C function in S-Function'
```

What This Issue Means

In R2020b, the compiler for model builds changed from a Windows® compatible C compiler to the QNX® Neutrino® C++ compiler. To accommodate this change, update S-Function code for C++ compatibility.

Tip Fortran S-Functions are not supported in R2020b and later releases of Simulink Real-Time.

Try This Workaround

To update S-Function code for C++ compatibility, modify the declaration of the S-Function in the header file.

For example, update this C S-Function declaration:

```
void getAllDataMyFunction(short);  
void myfunction_initialize(short, unsigned char*, short*);  
void myfunction_terminate(short, int);
```

Updated the code to this C++ S-Function declaration:

```
#ifdef __cplusplus  
extern "C" {  
#endif  
  
void getAllDataMyFunction(short);  
void myfunction_initialize(short, unsigned char*, short*);  
void myfunction_terminate(short, int);  
  
#ifdef __cplusplus  
}  
#endif
```

Before building the updated code, remember to remove all artifacts from previous model builds.

See Also

More About

- “External Code Integration”

External Websites

- How to mix C and C++